NEWS 2011



DEBUGGER, REAL-TIME TRACE, LOGIC ANALYZER



Always a Few Steps Ahead

Lauterbach has been developing tools for the embedded industry for over 30 years advocating this slogan. For most new debug technologies Lauterbach is the world leader and trend setter.

This has allowed us to gain the recognition of all the big semiconductor manufacturers. For many years, those involved in developing and implementing new technologies have favored collaboration with Lauterbach. This collaboration has inspired many ground breaking ideas to be transformed into advanced products.

In addition, Lauterbach is very customer focused. The desires and suggestions of our TRACE32 users provide a valuable contribution to our product development. In many cases, suggestions are put into practice immediately and are then included in the next released version of our debugger.

From this vantage point what trends does Lauterbach currently see? What technologies are soon to emerge in the market?

Android Debugging

Android debugging is certainly an important topic. Applications for mobile phones are increasingly being written architecture-independent for virtual machines (VM). Google's Android and its Dalvik VM are quite prevalent.

Complex errors that will only appear with the interplay of application, virtual machine, operating system and the underlying hardware have to be debugged. To do this it is necessary to have transparency through all of the software layers, from the Java application down to the Linux hardware drivers.

At the request of some mobile phone manufacturers, Lauterbach started developing an API for VM Debugging Awareness in the middle of 2010. Android is used here as a reference platform. The aim is to provide an open interface that allows providers of open-source and closedsource VMs to adapt their products for debugging with TRACE32. For information on VM Debugging Awareness and the current state of development, see the article "API for VM Debugging Awareness" on page 6.

CONTENTS

New Supported Processors	4
Tracing for Virtual Targets in Fast Models	5
API for VM Debugging Awareness	6
Extensions and New RTOS Versions	8
Serial Trace Port Usage Growing	9
Higher Transmission Rate for RTS	10
Energy Profiling with the CombiProbe	11
TRACE32 Expert Forum	12

Energy Profiling

Energy measurement for embedded systems has come more into focus with the increasing emphasis on global warming and "green" electronics systems. Every technical journal now contains many articles on battery-driven equipment and low-power microcontrollers. Prizes for innovation are increasingly being awarded for new technologies in this field.

However, in the mobile phone market standby and operating times have always been an important topic. For years, extensive energy reduction measures have been implemented in this area. But these measures only make sense if the software that controls an embedded system consistently uses all the energy-saving features of the hardware.

Since the beginning of 2006, Lauterbach tools have supported measuring arrangements that allow the simple comparison and analysis of the interplay between software and power consumption in an embedded system. This technology has also been available for the TRACE32 CombiProbe since mid 2010. For more information on "Energy Profiling with the CombiProbe", see page 11.

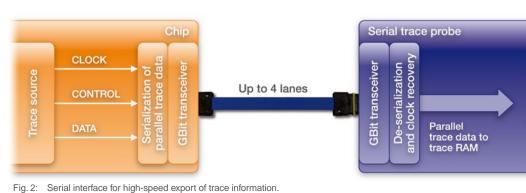
Multicore Debugging

Although multicore chips have been used in embedded systems for ten years and Lauterbach has had debuggers for them since 2001, this is still a highly dynamic topic. The current calls for greater visibility into the internal system operation are ensuring the integration of new trace cells within the debug infrastructure of the chips.

Originally, trace information was only generated for the individual cores, whereas today there are many other trace sources:

a) Trace sources that make transfers on chip-internal buses visible:

- ARM CoreSight with the AMBA AHB Trace Macrocell (HTM)
- RAM Trace Port for chips from Texas Instruments



the PC for years, used this technology for the first time in 2008 to export trace information via ARM's High Speed Serial Trace Port (HSSTP). At the same time. Lauterbach launched trace tools for this technology. »

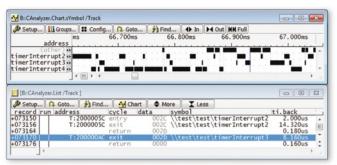


Fig. 1: Interrupt trace, Cortex M3.

- DMA and FlexRay trace for NEXUS Power Architecture
- MCDS with the System Peripheral Bus (SPB) and the Local Memory Bus (LMB) for the TriCore from Infineon

b) Trace sources that generate trace information for chipinternal IP (Intellectual Property), such as special interrupt traces (see Fig. 1).

c) Trace sources that permit the output of software-generated trace information, such as:

- Instrumentation Trace Macrocell (ITM) for ARM Core-Sight
- System Trace Macrocell (STM) for ARM CoreSight

The continuous development of the TRACE32 debugger ensures it is aware of these new trace sources and can provide easy configuration and a comprehensive analysis of the information provided.

Serial Trace Ports

Due to the extra trace data provided by this visibility into the internal chip processes, complex multicore chips and high-performance processors require more and more bandwidth and thus even faster trace ports.

In response chip manufacturers have developed serial trace ports (see Fig. 2) as an important innovation in the last few years. Hard-disk manufacturers, who have been using serial interfaces for high-speed data exchange with



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Fig. 3: Even demanding 4-GB trace memory analysis for Trace-based Debugging can be performed quickly.

In the meantime, there are other processor families with serial trace interfaces. For current developments in this area, see the article "Serial Trace Port Usage Growing" on page 9.

Bigger Trace Memory

Fast trace interfaces with their high data rates inevitably require more trace memory. Without this, it is impossible to capture a sufficiently large program section for troubleshooting and the analysis of the time behaviour for an embedded system.

However, providing more and more trace memory only makes sense if the necessary infrastructure for fast processing of the trace information is available. This applies particularly to demanding trace analysis functions such as *Trace-based Debugging* (see Fig. 3). The increasing capacity of SDRAM chips, fast PCs, and GB Ethernet interfaces enabled Lauterbach to launch the trace tool PowerTrace II with 4 GB memory in 2007.

In mid-2008, Lauterbach started developing a new method of trace recording and analysis, *Real-time Streaming*. This development was driven by customers' demands for long-term code coverage analysis, for comprehensive system runtime analyses and for a much longer trace recording time to locate infrequent errors.

The new feature of *Real-time Streaming* is that the trace data is transferred to the host while it is being recorded. The trace information is then analyzed on the host as soon as it is received. Optionally, the trace information can also be saved to the hard-disk while it is being analyzed.

Trace-Based Debugging

Trace-based Debugging (also known as CTS = Context Tracking System) allows re-debuggging of a traced program section.

TRACE32 makes this possible as it can reconstruct the state of the target system for each individual trace record in its PowerView GUI. This reconstruction includes:

- Source listing and task listing
- The register and memory contents
- Variable states and stack-frame
- and much more

After choosing a starting point for Trace-based Debugging, all of the debug commands can be used. These commands are executed by TRACE32 based upon the reconstruction from the trace recording. Many users of Trace-based Debugging appreciate the fact that they can also step backwards or return to the function start.

Trace-based Debugging also provides a series of other useful functions:

- Trace display in high-level language with all local variables
- Runtime analyses and function call tree
- Reconstruction of the trace gaps that can occur if more trace data is being generated than can be exported via the trace port

www.lauterbach.com/cts.html

Real-time Streaming works only if all processing steps for the trace data run at optimal speed. This applies to transfer and analysis, as well as the systematic search for trace information in a file saved to the hard disk.

Conventional tracing also profits from many of the new speed optimizations. For example, there are plans to implement the trace-data compression (developed for *Real-time Streaming*) also for conventional tracing. For details on the trace-data compression, see page 10.

Outlook

In addition to the current trends, there are a large number of new developments in debug technology. When you browse through our 2011 newsletter, you will probably discover one or two of these that might help with your project. We will be demonstrating several of them live at many shows worldwide throughout the year.

New Supported Processors

New derivates	
Actel	LA-7844 (Cortex-M) • A2F060, A2F200, A2F500
AppliedMicro	LA-7723 (PPC400) • APM80186, APM821x1 • APM86290 LA-7752 (PPC44x) • PPC460SX
ARM	LA-7843 (Cortex-A/R) Cortex-A15 Cortex-A15 MPCore LA-7844 (Cortex-M) Cortex-M4 SC000, SC300
Atmel	LA-7844 (Cortex-M) • AT91SAM3S, AT91SAM3N LA-3779 (AVR32) • AT32UC3A/B/C/D/L
Broadcom	LA-7760 (MIPS32) • BCM3549/35230/4748 • BCM5354/5358/5331X • BCM6816/6328/6369 • BCM7407/7413/7420
Cavium	LA-7761 (MIPS64) • CN63XX
Ceva	LA-3711 (CEVA-X) • CEVA-X1643, CEVA-XC
Cortus	LA-3778 (APS) • APS3/B/BS/S
Cypress	LA-7844 (Cortex-M) • PSoC5
Faraday	LA-7742 (ARM9) • FA726TE
Freescale	LA-7736 (MCS12X) • MCS9S12GC/GN/Q LA-7732 (ColdFire) • MCF5301x, MCF5441x LA-7845 (StarCore) • MSC8156 LA-7742 (ARM9) • i.MX28 LA-7843 (Cortex-A/R) • i.MX53 LA-7844 (Cortex-M) • Kinetis

Freescale (Cont.)	LA-7753 (MPC55xx/56xx) • MPC5602D/P • MPC564XA/B/C/S • MPC567XF/R LA-7729 (PowerQUICC II) • MPC830X LA-7764 (PowerQUICC III) • P10xx, P20xx, P40xx • P3041 (2H/2011) • P5010, P5020 (2H/2011)
Fujitsu	LA-7844 (Cortex-M) • FM3
Infineon	LA-7756 (TriCore) • TC1182, TC1184 • TC1782, TC1782ED • TC1784, TC1784ED • TC1791, TC1791ED • TC1793, TC1793ED • TC1798, TC1798ED LA-7759 (XC2000/C166S V2) • XC22xxH/I/L/U • XC23xxC/D/E/S • XC27x2/x3/x7/x8 • XE16xFH/FU/FL
Intel®	LA-3776 (Atom™/x86) • E6xx, Z6xx, N470 • Core i3/i5/i7, Core2 Duo
Lantiq	LA-7760 (MIPS32) • XWAY xRX200
LSI	LA-7765 (ARM11) • StarPro2612, StarPro2716 LA-7845 (StarCore) • StarPro2612, StarPro2716
Marvell	LA-7742 (ARM9) • 88F6282, 88F6283, 88F6321 • 88F6322, 88F6323 LA-7765 (ARM11) • 88AP510-V6 LA-7843 (Cortex-A/R) • 88AP510-V7
MIPS	LA-7760 (MIPS32) • MIPS M14K, MIPS M14KC
Netlogic	LA-7761 (MIPS64) • XLR, XLS
NXP	LA-7844 (Cortex-M) • LPC11xx • EM773



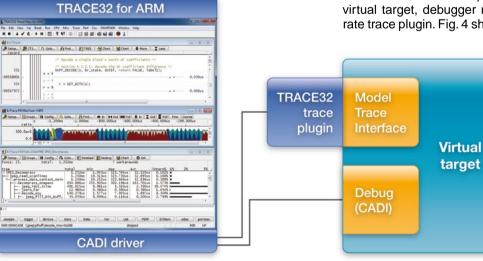
New derivates			Texas Instruments	LA-3713 (MSP430) • MSP430xG461x
Ralink	LA-7760 (MIPS32) • RT3052, RT3662			 MSP430x20x1/x2/x3 LA-7742 (ARM9)
Renesas	as LA-3777 (78K0R/RL78) • 78K0R/Hx3/Lx3/lx3 • 78F804x, 78F805x • RL78/G12, RL78/G13 LA-3786 (RX)			 AM1707/1808/1810 LA-7843 (Cortex-A/R) OMAP36xx LA-7838 (TMS320C6x00) OMAP36xx
STMicro- electronics	• RX610/6108/621/62N/630 Micro- LA-7753 (MPC55xx/56xx)		Toshiba	LA-7742 (ARM9) • TMPA900, TMPA910 LA-7844 (Cortex-M) • TMPM330, TMPM370
			Trident	LA-7760 (MIPS32) • HiDTV PRO-QX
ST-Ericsson	LA-7843 (Cortex-A/R) DB5500, DB8500		Wintegra	LA-7760 (MIPS32) WinPath3, WinPath3-SL
Tensilica	LA-3760 (Xtensa) • LX3		Zoran	LA-7760 (MIPS32) • COACH 12

Tracing for Virtual Targets in Fast Models

Lauterbach has supported tracing for ARM Fast Models since November 2010.

To avoid having to wait for the first hardware prototypes before starting software development, software models of the hardware are often used. With Fast Models, ARM offers its customers a software package for programming models for ARM-based designs.

Since 2008, Lauterbach has supported the debugging of Fast Models over the CADI interface. It has now introduced support for the Model Trace Interface, which was introduced for Fast Models with Version 5.1. To prepare the trace information appropriately and buffer it in the virtual target, debugger manufacturers can load a separate trace plugin. Fig. 4 shows an overview of the interplay



of TRACE32 and Fast Models.

The Model Trace Interface provides program trace as well as data trace. Thus all standard TRACE32 profiling features are usable.

Detailed information on debugging virtual targets:

www.lauterbach.com/ frontend.html

Fig. 4: TRACE32 supports the debugging and tracing of virtual targets.

API for VM Debugging Awareness

Since 2006, Lauterbach has supported the debugging of Java applications for the Java Virtual Machines J2ME CLDC, J2ME CDC and Kaffe. Since virtual machines are increasing in popularity, the number of providers is growing. Nowadays not all of these virtual machines are open-source. To enable VM providers and their customers to adapt debugging flexibly for their VM, Lauterbach has been working on a solution since mid-2010.

The Android Dalvik Virtual Machine implemented for ARM cores is used as a reference for the development of a VM API for stop-mode debugging.

Two Debug Worlds

For developers, Android is an open-source software stack consisting of the following components (see Fig. 5):

- A Linux kernel with its hardware drivers.
- Android Runtime with Dalvik Virtual Machine and a series of libraries: classic Java core libraries, Androidspecific libraries, and libraries written in C/C++.
- Applications programmed in Java and their supporting Application Framework.

Software for Android is written in various languages:

- The Linux kernel, some libraries, and the Dalvik Virtual Machine are coded in C, C++, or Assembler.
- VM applications and their supporting Application Framework are programmed in Java.

Each block of code is tested in its own separate debug world.

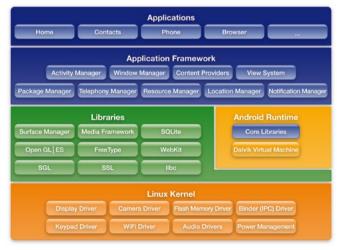


Fig. 5: The open-source Android software stack.

Debugging C/C++ and Assembler Code

The Android part coded in C/C++ and Assembler can be debugged on the target hardware over the JTAG interface in stop-mode. In stop-mode debugging, the TRACE32 debugger communicates directly with the processor of the Android hardware platform (see Fig. 6).

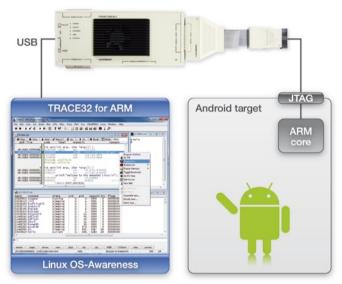


Fig. 6: In stop-mode debugging, the debugger communicates directly with the processor on the Android hardware platform.

A characteristic of stop-mode debugging is that when the processor is stopped for debugging, the whole Android system stops.

Stop-mode debugging has some big advantages:

- It needs only a functioning JTAG communication between the debugger and the processor.
- It needs no debug server on the target and is therefore very suitable for testing release software.
- It permits testing under real-time conditions and therefore enables efficient troubleshooting for problems that only occur in such conditions.

At present, stop-mode debugging does not support the debugging of VM applications such as on the Dalvik VM. Therefore transparent debugging through all of the software layers is not yet possible.

Debugging Java Code

Java code for Android is usually tested with the Android Development Tools (ADT) integrated into Eclipse. »



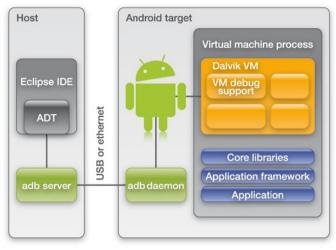


Fig. 7: The Android Development Tools (ADT) integrated in Eclipse for debugging Java code.

The adb server – adb stands for Android Debug Bridge – on the host communicates over USB or Ethernet with the adb daemon on the target (Fig. 7).

Prerequisites for debugging with ADT are VM applications specially compiled for debugging and Android debug support (adb daemon) running on the hardware platform.

Debugging Java code with ADT is comfortable. However, there are a few cases in which ADT cannot help you. These are:

- Errors that first occur with the release code.
- Errors that first occur when the Java application interacts with a service offered in C/C++ or a Linux hardware driver.
- Debugging following a communication breakdown between adb server and adb daemon.

VM Aware Stop-Mode Debugging

To enable thorough testing of an Android system from the Java application down to the Linux hardware driver under real-time conditions, Lauterbach is currently adding VM debugging awareness to its stop-mode debugging.

The JTAG debugger communicates directly with the processor on the Android hardware platform. The debugger can therefore access all system information after the processor stops. The "fine art" for the debugger is now to find the correct information and make it easy to understand for the user, abstracted from bits and bytes.

One abstraction level has given TRACE32 users the option of debugging operating system software even over

several virtual address spaces. Another abstraction level, up to now independent of operating-system debugging, is Java debugging.

To debug applications running on VMs in systems like Android, where the VMs themselves are instantiated within the operating-system processes, operating-system debugging and Java debugging now have to be combined. To implement this new complexity, Lauterbach is developing a new, open, and easy-to-expand solution.

The Open Solution

In the future, stop-mode debugging from Lauterbach will support the following abstraction levels:

- High-level language debugging
- Target-OS debugging awareness
- VM debugging awareness

High-level language debugging is a fixed component of the TRACE32 software and is configured for a program with the loading of the symbol and debug information.

Target-OS debugging awareness must always be configured by the TRACE32 user. There are example configurations available for all common operating systems. The RTOS API provides an option to be customized for proprietary operating systems.

VM debugging awareness is a fixed component of the TRACE32 software for J2ME CLDC, J2ME CDC and Kaffe. All other virtual machines have to be adapted individually with the VM API. A ready-to-use configuration is available for the very popular Android Dalvik VM.

The open solution, both for the operating system and for the virtual machine, enables providers of closed-source VMs to write a TRACE32 VM awareness for their product and offer it to their customers. »

Dalvik Virtual Machine

Dalvik is the name of the virtual machine used in Android. The Dalvik Virtual Machine is a software model of a processor that executes byte code derived from Java. Virtual machines permit the writing of processor-independent software. If you switch to a new hardware platform, you only have to port the virtual machine.

Software compiled for a VM runs automatically on any platform to which this VM is ported.

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Fig. 8: For the reference implementation, Linux OS-awareness and Dalvik VMawareness have to be loaded in TRACE32.

The Reference Implementation

To be able to debug on an ARM-based Android target TRACE32 requires the following extensions (see Fig. 8):

- A Linux OS-awareness as provided by Lauterbach since 1998.
- A Dalvik VM-awareness, which can be downloaded from the Lauterbach homepage. This just has to be configured for the platform used.

www.lauterbach.com/vmandroid.html

It is now possible to identify and list all Java applications now being run (EXTension.VMList in Fig. 8) and to analyze and view the VM stack for a selected Java application (EXTension.VMView in Fig. 8). The next step planned is to display the source code currently being run by the VM. The aim of the development is of course stop-mode debugging for VM applications with all the functions of a modern debugger.

New Integrations with Third-Party Tools

The TRACE32 debuggers include an interface for external access (API). This interface can be used to integrate with third-party tools. The following integrations are planned for 2011:

- EFI/UEFI (Unified Extensible Firmware Interface) promoted by the Unified EFI Forum on x86
- Matlab/Simulink from MathWorks
- µC/Probe from Micriµm Inc.

Extensions and New RTOS Versions

New S	upported	RTOS
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DSP/BIOS for ARM	Q2/2011
OSEK/ORTI SMP	Q2/2011
T-Kernel for ARM	available
VDK for Blackfin	available
Windows Embedded Compact 7 for ARM	available
Windows Phone 7 for ARM	available
μC/OS-III for ARM	available

- TRACE32 scripts were adapted for Timesys embedded Linux.
- OSEK/ORTI now ensures that NEXUS ownership trace messages are generated for task changes. This enables TRACE32 to make task-aware run-time measurements for the MPC55xx/MPC56xx, even if NEXUS generates no data trace messages.

The following version adaptations have been made or are planned:

- OSEck 4.0
- QNX 6.5.0
- Symbian^3 for ARM
- Symbian⁴ planned for Q1/2011
- Windows CE6 for Atom[™]



Serial Trace Port Usage Growing

Faster, higher, stronger! Not only is this the motto of many sports – it has even been raised to a core principle in microelectronics. Ever faster clock speeds and a greater parallelization of processing steps have given us an astonishingly constant increase in processing speed for decades. It is no wonder that designers have also followed this motto for the transmission of trace information in embedded designs.

The trace interface, over which the processors deliver the detailed information on the operation of their inner processes, has struggled to keep up with the growing flood of information. For many developers of embedded systems it would be unthinkable to undertake a development without this important information, so all sorts of efforts have been made to increase the data throughput of the trace interface. For many years the increase in clock frequency and a greater bus-width at the trace port were an effective way of increasing data volumes.

However, these measures have their price. Not only does a wider trace port take up highly coveted package pins but poor signal quality at higher clock frequencies requires compensation on all signals from the trace bus. Thanks to the sophisticated algorithms of its AutoFocus technology, Lauterbach is able to ensure error-free recording of highfrequency trace signals.

As processor architectures continue to gain in speed and complexity through parallelization, the trace interfaces are starting to use a high-speed data transfer method that has been in use in other areas for a long time. A high-speed serial transmission is used in SATA, Fibre Channel, PCI Express, and USB3.0 (SuperSpeed USB). The extremely high data rates more than compensate for the disadvantage of only a few differential data lines.

The integration of high-speed serial interfaces on the chip is expensive and can initially cause problems. As just one example, the I/O pads have to be operated at a much higher speed. But with the increasing experience in the implementation of serial interfaces in the gigahertz range the knowledge gained can be used to solve many of the problems arising with the serial trace ports.

In 2008, ARM implemented this technology with its High Speed Serial Trace Port – HSSTP for short. This was quickly followed by:

- AMCC with the Titan
- Freescale with the QorlQ processors P4040 and P4080
- Marvell with the SETM3



Fig. 9: Following firmware and software adaptations, a universal hardware supports the most varied protocols of serial trace interfaces.

Lauterbach had designed a hardware interface for the serial trace in 2008. A universal preprocessor (see Fig. 9) was developed on the basis of the Aurora protocol. Only the firmware and software have to be changed to record any of the alternative protocols. This means that our system is already prepared for further variants of serial trace protocols.

The large volume of trace data obviously requires a correspondingly large trace memory. This is provided by the PowerTrace II with up to 4 GBytes.

Supported S	erial Trace Ports	
AMCC	APM83290 Program flow	2009
ARM-HSSTP	ETMv3, PTM, CoreSight ETMv3, CoreSight PTM	2008
	Program flow, Data flow and Context-ID	
Freescale	NEXUS QorlQ P4040 and P4080	2010
	Branch Trace and Owner- ship Trace Messages, Data Write Messages	
Marvell-SETM3	CoreSight ETMv3 Program flow, Data flow and Context-ID	2009

Higher Transmission Rate for Real-Time Streaming

"Real-time Streaming" means transferring trace data to the host whilst it is being recorded and analyzing it there immediately.

- It is currently implemented for the ARM trace protocols ETMv3, PTM and software-generated trace information as exported by the CoreSight ITM or STM.
- It is supported by the TRACE32 debug and trace tools CombiProbe and PowerTrace II.

Hardware Compression for PowerTraceII

For CPU-intensive applications and multicore systems *Real-time Streaming* requires the transmission of large volumes of data from the trace tool to the host, especially for PowerTrace II. To make TRACE32 fit for these application scenarios, the trace data is compressed by PowerTrace II before being transferred to the host. This feature has been supported by the TRACE32 software since December 2010.

The maximum transmission rate to the host is still the bottle-neck for *Real-time Streaming*. Even with a peerto-peer GB Ethernet interface between PowerTrace II and the host, the maximum is currently only about 500 MBit/s net. This maximum transmission rate has to be sufficient to transfer all data at the trace port without loss to the host. By implementing FPGA-based hardware compression in PowerTrace II, the transmission rate to the host was raised to 3.2 GBit/s.

To be able to estimate the actual data volume to be transmitted, it is important to know the conditions of *Real-time Streaming:*

- 1. The main applications for *Real-time Streaming* are code coverage and run-time measurements. For both functions, it is sufficient if only the program trace information is exported. To get a very accurate run-time measurement, cycle-accurate tracing can be enabled.
- 2. For a realistic estimate of the necessary data rate, you just have to consider the average load at the trace port. Peak loads at the trace port are intercepted by PowerTrace II, which can be considered as a large FIFO (up to 4GB). Fig. 10 shows an overview of the average/maximum load at the trace port for Cortex cores. The application running on the Cortex core ultimately determines the actual load.

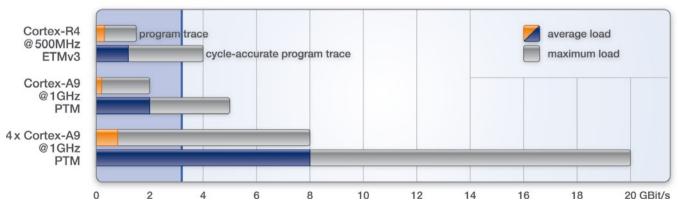
Pure Long-Time Trace

If trace data is analyzed and also saved to the hard-disk during *Real-time Streaming*, Lauterbach considers this a *Long-time Trace*.

To provide long-time tracing for other trace protocols such as Nexus, Lauterbach is now offering pure streaming onto the hard-disk without simultaneous analysis. This means that trace recording of up to 1 tera-frames is possible for a 64-bit host operating system. It goes without saying that long-time tracing only works if the average data rate at the trace port is not exceeding the maximum transmission rate of the host interface in use.

For detailed information on *Real-time Streaming* and *Long-time Trace*, go to the Lauterbach homepage at:

www.lauterbach.com/tracesinks.html



3.2 GBit/s max. transmission rate

Fig. 10: A transmission rate of 3.2 GBit/s is usually enough to transfer program trace information to the host while it is being recorded.



Energy Profiling with the CombiProbe

The TRACE32 CombiProbe can now also be used for measuring the energy used by applications.

The following analyses are possible:

- The current/voltage profile at up to three measurement points can be displayed directly linked to the code running on the processor.
- The energy consumption of the entire system can be analysed for the individual functions.

The following questions can now be dealt with by the CombiProbe:

- Which part of a program uses the most energy?
- Are there any unexpected power peaks?
- Does the program always switch the microcontroller to the right power-saving mode?
- What influence does a program modification have on the energy requirements of an embedded system?

To determine the energy consumption for every point of the program, the following measurement data has to be collected:

- The program flow being exported via the trace port of the processor.
- The current and voltage profile measured at suitable measurement points on the target hardware.

The current and voltage development for up to three power domains can now be identified by connecting a *TRACE32 Analog Probe* to the CombiProbe.

CombiProbe

The CombiProbe is a debug cable that also contains a 128MB trace memory.

The CombiProbe was specially developed for processors with a 4-bit trace port. Program flow recording is currently supported for the following trace protocols:

- ARM-ETMv3 in continuous mode (ARM)
- IFLOW Trace for PIC32 (Microchip)
- MCDS Trace for X-GOLD102 and X-GOLD110 (Infineon)

www.lauterbach.com/cobstm.html

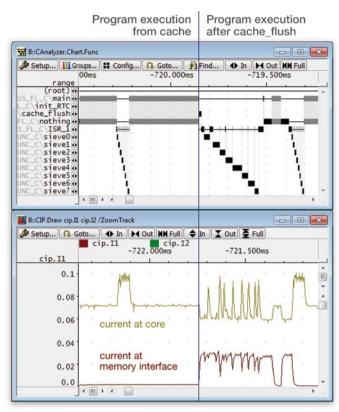


Fig. 11: A program section not running from the cache needs more time and uses more current.

Since all measurement data is time-stamped by the global timer of the CombiProbe, you can quickly and easily see the direct connection between executed program code and the power consumption as well as the voltage profile of the system.

Fig. 11 shows that a program section running from external memory instead of cache not only needs much more processing time but also uses more power at the external memory.

Fig. 12 shows the energy consumption as a statistical analysis.

Detup	iii Groups	Config	Goto	E Detailed	1 Nesting	H Chart	O Init	
		fu	ncs: 14.	to	tal: 261.7	37mJ intr:	98.184mJ	
		range tot	tal in	nin	max	avr	count	L
		(root) 1		-	163.554mJ	163.554m3	-	1.
sinus fl	STNUS EL	main 1		-	163.540mJ	163.540mJ	1. (0/1)	111
	S_FL_C\in		24.646u3	24.646uJ	24,646uJ		1.	
		flush		8,732uJ			176.	
	US_FL_C\n		04.771m3	0.000			1079368.	
	INUS FL C		98.184mJ	20.229uJ	346, 980uJ		1755.	
f1\SIEVE	0_FUNC_C	sieve0	9.865mJ	1.947uJ	32.718uJ	5.621uJ	1755.	
f1\SIEVE	1_FUNC_C	sievel 1	L1.368mJ	2.536uJ	39.485uJ	6.478uJ	1755.	
	2_FUNC_C\		9.063mJ	2.410uJ	28.901uJ	5.164uJ	1755.	
	3_FUNC_C\		LO. 937mJ	2.574uJ	38.119uJ	6.232uJ	1755.	
	4_FUNC_C\		L3.244mJ	2.640uJ	50.595uJ	7.547uJ	1755.	
	5_FUNC_C		LO. 098mJ	2.504uJ	34.293uJ	5.754uJ	1755.	
	6_FUNC_C		9.912mJ	2.393uJ	33.921uJ	5.648uJ	1755.	
f]\STEVE	7_FUNC_C	sieve7	7.620mJ	2.576uJ	19.322uJ	4.342uJ	1755.	

Fig. 12: The minimum, maximum, and average energy consumption of individual functions.



Expert Forum – Interacting with the User



Fig. 13: Technical details are clarified in a technical discussion.

Review – ARM Expert Forum

Twice last year, customers and interested professionals had the opportunity to discuss the debugging of ARM cores with our TRACE32 experts. The "Expert Forum" on May 5, 2010 was booked out so fast, that we decided to run another on November 24 and 25. This was conducted in English to give European customers a chance to participate.

At both functions, the participants were able to get information about all aspects of debugging and tracing on ARM cores. Our experts provided a deep insight into the relationship of the individual components as well as the special possibilities offered by the different cores. The topics ranged from connectivity options for the different debug and trace ports, up to the optimal analysis of trace information.

In particular, the forum focused on the examination of multicore systems. The TRACE32 debug and trace concepts for AMP and SMP systems were amplified and illustrated with various configuration examples.



Using the example of Linux as a target operating system, some of the many different requirements that a modern debugging system has to meet in today's applications were shown. This lecture was rounded off with a look at Lauterbach's new development for Android debugging.

A particular highlight was the guest lecture by lan Johnson (ARM Ltd.), who presented details of ARM processors as well as an interesting overview of future developments.

Outlook – Expert Forum Automotive

The positive feedback from all of the participants and the strong demand for further events of this kind demonstrate to us how important it is to have a function where users and developers of our debug systems can exchange views on a one-to-one basis.

Expert Forum Automotive on May 18, 2011			
TRACE32 Product Overview			
Development of AUTOSAR System	s/Components with TRACE32		
TriCore Track	Power Architecture Track		
 News Concurrent Debugging of TriCore and PCP MCDS/Trigger Language OCTL Profiling Q&A with TRACE32 Experts 	 News Multicore Debugging/Tracing NEXUS-based Profiling Q&A with TRACE32 Experts 		

Therefore, we plan to hold further expert forums in 2011. On May 18, 2011, the topic will cover everything about debug solutions for the automotive field. We will focus on the processor families TriCore from Infineon, MPC55xx/ MPC56xx from Freescale, as well as the SPC56xx from ST. One emphasis will be AUTOSAR.

For an overview of the planned topics, see the above agenda. For more detailed information, please check our homepage as the date gets closer.

KEEP US INFORMED

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